

Decentralized Coverage Control Problems For Mobile Robotic Sensor And Actuator Networks (IEEE Press Series On Systems Science And Engineering) By Andrey V. Savkin;Teddy M. Cheng;Zhiyu Li

By Andrey V. Savkin;Teddy M. Cheng;Zhiyu Li

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In this paper a novel problem of adaptive awareness coverage is formulated. We model the mission domain using a density function which characterizes the importa

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Decentralized, Adaptive Coverage Control for broader applications of adaptive control methodologies to decentralized control problems in unknown

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DECENTRALIZED COVERAGE CONTROL PROBLEMS FOR MOBILE ROBOTIC SENSOR AND NETWORKS : Andrey V. Savkin, Teddy M. Cheng, IEEE Press Series on Systems Science
<http://www.herrerobooks.com/es/libro/9781119025221/andrey-v-savkin/decentralized-coverage-control-problems-for-mobile-robotic-sensor-and-actuator-networks>

Teddy m. Cheng , Andrey v. Savkin, Decentralized control for mobile robotic sensor network generation wireless mobile networks, Mobile Information Systems, v.7
<http://dl.acm.org/citation.cfm?id=5509>

Pris 1606 kr. K p Estimation and Control Over Communication Networks (9780817644949) av Alexey S Matveev, Decentralized Coverage Control Problems For Mobile R
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standard h_2 and h_∞ control problems. IEEE Trans. Autom. Control 34 Decentralized, adaptive control for coverage with fuzzy coverage control for
<http://link.springer.com/article/10.1007%2Fs11071-012-0340-3>

This paper describes decentralized control These utility functions are studied in geographical optimization problems Coverage control for mobile sensing
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Project Number IMURA0411 Monash MainSupervisor (Name, The research problem We would also like to extend results to decentralized coverage control design on

http://iitbmonash.org/Resources/Research_Opps_PDFs/IMURA_0411.pdf

In this paper, we consider the problem of decentralized dynamic coverage control for mobile sensor networks in an environment with unknown obstacles.

<http://onlinelibrary.wiley.com/doi/10.1002/asjc.532/abstract>

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Decentralized Formation Control and Connectivity Maintenance of coverage control, mation control problem. In Section III,

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Distributed Coverage Control with Sensory Feedback for Networked Robots Author: Schwager M, McLurkin J, Rus D. Publication: Conference in Philadelphia, PA. Year:

<http://mrsl.rice.edu/papers/distributed-coverage-control-sensory-feedback-networked-robots>

Decentralized Coverage Control for Multi-Agent Systems with Nonlinear Dynamics: sensor networks, coverage problem, nonholonomic mobile robots, collision avoidance:

<http://adsabs.harvard.edu/abs/2011EITL..94....3D>